### 2022 Design and Prototype Semi-Finalists

#### Solid Magnetic Boots

Students: Teacher: School:	Evan Coleman, Damion Thomas, Hayden Bate Steven Marcus Cypress Springs, Texas		
Students: Teacher:	Julio Garcia, Juan Chavez Steven Marcus		
School:	Cypress Springs, Texas		
Students: Teacher:	Jacob Dreger, Cooper Gassman, Noah Felder, Daniel Wells, Matthew Heer Matt Heer		
School:	Platteville, Wisconsin		
Students:	Rose Thomas, Carter Garrison, Ryan Torlin		
School:	Cherokee Trail, Colorado		
Students:	Ben Miller, Tim Bowser		
School:	Kettering Fairmont, Ohio		
Students: Teacher:	Gabriel Nelson, Joshua Goudy, Nicholas Morledge-Hampton Fric Anderson		
School:	Billings Career Center, Montana		
Students: Teacher:	Shane Kuo, Damian Wilson, Kendall Meyers, Calvin Erickson Vince Stornello, Donna Himmelberg		
School:	Fairport, New York		



# **CYSPRINGS H.S. ENGINEERING DESIGN II CYPRESS FAIRBANKS ISD** CYPRESS, TX

# NASA HUNCH PROGRAM

## **TEAM NAME - STEEL** WHEELS

**TEAM MEMBERS -**1. EVAN COLEMAN 2. DAMION THOMA'S 3. HAYDEN BATE

**INSTRUCTOR - STEVEN** MARCUS

NASA HUNCH MENTOR -**GLEN JOHNSON** 













-Slides

GENERAL INFO- ON ONE SHOE THERE IS A WHEEL IN THE SHOE, ON THE OTHER SHOE WE HAVE A MAGNET BELOW THE ASTRONAUTS TOES TO ACT AS IF SKATEBOARD WHERE ONE SIDE STAYS ON THE STEEL SHELL OF SPACECRAFT (SKATEBOARD) AND THE OTHER FOOT ON THE SHELL OF THE SPACECRAFT ACTING AS THE GROUND PROVIDING THE PROPULSION OF THE SKATE,

**OBJECTIVE: TO ALLOW AN EASIER METHOD** TO SPACE WALK INSTEAD OF FLOATING YOU CAN ROLL ON THE SURFACE OF THE SPACECRAFT

MATERIALS- WHEEL: CIRCULAR MAGNETS **BOTTOM OF SOLE: STEEL TOP OF SOLE: WOOD** 

**ISSUES: THE MAGNET HAS A STRONG HOLD** SO IT MIGHT BE HARD TO ROLL THE WHEEL

**TECHNIQUES: ON ONE SHOE YOU USE** MAGNET TO GET ENOUGH POWER TO ROLL ON THE OTHER YOU USE THE WHEEL TO ROLL

SOLUTIONS: SINCE THE HOLD IS STRONG THE MAGNETIC WHEEL ALLOWS THE ASTRONAUT TO SLIDE ON SPACECRAFT

**PROBLEMS: THE SPACE WALK IS** DANGEROUS AND IT USES A JETPACK TO GET TO PLACES AROUND THE SPACECRAFT, THE SHOES WILL ELIMINATE THE USE OF FUEL DURING SPACEWALKS AND INSTEAD IT USES HUMAN MECHANICS TO GET AROUND CHALLENGES



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![](_page_4_Picture_5.jpeg)

![](_page_4_Picture_6.jpeg)

SHOES TEST

![](_page_4_Picture_8.jpeg)

THE MAGNETIC BOOTS ARE SUPPOSED TO HELP THE ASTRONAUTS WITH A WAY OF SUSTAINABILITY WHEN BEING OUTSIDE THE SHUTTLE TRYING TO FIX PROBLEMS. MATERIAL:

**OUR ISSUE WOULD BE THE MAGNETS FITTING ON THE** SOLE. MAKING SURE THE MEASUREMENTS ARE CORRECT AND HAVE THE RIGHT AMOUNT OF MAGNET FORCE **DISTRIBUTION.** 

WE ENVISIONED OUR PROJECT IN OUR HEADS AND WE SKETCHED IT. WE DREW IT IN INVENTOR AND AUTOCAD. SOLUTIONS:

WE USED THE EXACT DIMENSIONS, USED CARDBOARD AS **OUR PROTOTYPE, AND FIGURED OUT HOW TO PLACE THE MAGNETS BY EXPERIMENTING IN DIFFERENT POSITIONS USING THE PROTOTYPE.** 

MAKING SURE THE MAGNETS HAD ENOUGH FORCE TO WITHSTAND 20 POUNDS.

**BEING ABLE TO GET THE MAGNETS. CUT OUT THE SOLE** AND HOLES WHERE THE MAGNETS ARE PLACED.

## **OBJECTIVES:**

RUBBER SHEET METAL SHOES GLUE • MAGNETS BOOT •

## **ISSUES:**

## **TECHNIQUES:**

## **PROBLEMS:**

## **CHALLENGES:**

# Magnetic Boots for SpaceX Human Landing System

## Jacob Dreger, Cooper Gassman, Noah Felder, Daniel Wells

Matthew Heer Platteville High School

![](_page_5_Picture_4.jpeg)

## • Criteria

- The ability to turn the boots on and off
- Should hold at least 20 pounds on 301 stainless 0
- Easy to put on and easy to turn on and off 0
- o Simple, easy to replicate
- Constraints
  - Can't be easy to take off
  - No electronics 0

![](_page_5_Picture_13.jpeg)

Pros	Cons	Pros	Cons
<ul> <li>Simple Less force</li> </ul>	<ul> <li>Rotate instead of lever</li> </ul>	<ul> <li>Simple</li> <li>Lever</li> <li>design</li> </ul>	<ul> <li>More effort</li> <li>May be inconsistent</li> <li>Fabric required in design</li> </ul>

![](_page_6_Picture_0.jpeg)

AstroMag (Switchable Magnet Boot/Slipper for Space Walks) Kettering Fairmont High School Brett Jenkins By: Ben Miller and Tim Bowser

![](_page_7_Picture_1.jpeg)

We have created a non-powered switchable magnet system on a boot/slipper allowing astronauts to go on space walks on a magnetic side of a space shuttle.

![](_page_7_Picture_3.jpeg)

![](_page_7_Picture_4.jpeg)

![](_page_7_Picture_5.jpeg)

### **Billings Career Center**

#### Magnet Boots

Eric Anderson

Selling Points:

- Very Simple
- Very Lightweight
- Hands Free
- Deliberate Movement
- Configurable
- No Wiring/Battery Necessary

![](_page_8_Picture_10.jpeg)

Left: Gabriel Nelson Middle: Joshua Goudy Right: Nicholas Morledge-Hampton

![](_page_8_Picture_12.jpeg)

#### **Demonstration Videos**

https://youtube.com/shorts/92O1PvbZ2DY?feature=share https://youtube.com/shorts/4SmWiPX4CT4?feature=share

## Magnetic Boots

Mr. Stornello's Class Shane Kuo, Damian Wilson, Kendall Meyers, Calvin Erickson

The boot attachment uses one motor that moves an egg-shaped protrusions 90° downwards to separate the boot from the magnetic surface. Two smaller magnets reside close to the back, providing attraction. As of the presentation of our shoe the design uses one switch to control when the egg raises and lowers the shoe, facilitating transportation and storage. The big toe will be able to interact with the switch on the roof of the inside of the boot. After the CDR, we plan to add a separate power switch to allow for locking in place to prevent accidental disengagement from surfaces.

![](_page_9_Picture_3.jpeg)

![](_page_9_Picture_4.jpeg)

![](_page_9_Picture_5.jpeg)

![](_page_9_Picture_6.jpeg)

![](_page_9_Picture_7.jpeg)

Why is our design useful?

The main advantages of our magnetic boot attachment design are:

- Simple but feasible with manageable components;
- Scaleable with potential for customization;
- 3. Energy efficient with no need for a large power supply.